# Linear Algebra

Lecture 7: Linear Operators I

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#### Linear Operators: Preliminaries

A linear operator in a vector space *V* is a linear map  $\mathcal{A} : V \to V$ .

The matrix of an operator  $\mathcal{A}$  in a basis  $\{e_1, \dots, e_n\}$  is a matrix  $A = (a_{ij})$ , where  $\mathcal{A}(e_j) = \mathcal{A}e_j = \sum_{i=1}^{n} a_{ij}e_i$  (the columns of A). That is,  $(\mathcal{A}e_1, \dots, \mathcal{A}e_n) = (e_1, \dots, e_n)A$ .

If y = Ax, then Y = AX in the matrix form.

#### **Transition of Coordinates**

Let 
$$(e'_1, ..., e'_n) = (e_1, ..., e_n)C$$
. Then we have  
 $(\mathcal{A}e'_1, ..., \mathcal{A}e'_n) = (\mathcal{A}e_1, ..., \mathcal{A}e_n)C =$   
 $= (e_1, ..., e_n)AC = (e'_1, ..., e'_n)C^{-1}AC$ . Thus,  
 $A' = C^{-1}AC$ .

Main question: how can we change a basis in such a way that the matrix has a simple form? Invariant subspaces and eigenvectors are coming!

#### **Invariant Subspaces**

A subspace  $U \subset V$  is invariant for  $\mathcal{A} : V \to V$ if  $\mathcal{A}U \subset U$ , i.e.  $\mathcal{A}u \in U$  for any  $u \in U$ .

The restriction  $\mathcal{A}|_U$  is an operator in U.

In the basis of *V* that agrees with *U* the matrix of  $\mathcal{A}$  has the following form:  $\begin{pmatrix} A_0 & B \\ 0 & C \end{pmatrix}$ , where  $A_0 = \operatorname{Mat}(\mathcal{A}|_U)$ 

#### **Direct Sum of Invariant Subspaces**

If  $V = V_1 \bigoplus \cdots \bigoplus V_k$ , where all  $V_i$  are

invariant, then  $A = \begin{pmatrix} A_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & A_{\nu} \end{pmatrix}$ , where

 $A_j = \operatorname{Mat}(\mathcal{A}|_{V_j}).$ 

Simple example:  $A = \text{diag}(a_1, a_2)$ . Here  $\mathbb{R}^2 = \langle e_1 \rangle \bigoplus \langle e_2 \rangle$ .

### **Eigenvectors and Eigenvalues**

A non-zero vector  $v \in V$  is an eigenvector of  $\mathcal{A}$  if  $\mathcal{A}v = \lambda v$  for some  $\lambda \in \mathbb{F}$  (the field).

The corresponding number  $\lambda \in \mathbb{F}$  is called an eigenvalue of  $\mathcal{A}$  corresponding to v.

In the basis of eigenvectors  $v_1, ..., v_n$ :  $A = \text{diag}(\lambda_1, ..., \lambda_n).$ 

#### **Eigenvectors and Eigenvalues**

If  $Av = \lambda v$  for some  $\lambda \in \mathbb{F}$ , then  $\langle v \rangle$  is invariant subspace.

Geometrically, eigenvectors are exactly the directions, where the operator acts by stretching of a space by the corresponding eigenvalues.

#### **Characteristic Polynomial**

 $\mathcal{A}v = \lambda v$  for some  $\lambda \in \mathbb{F}$  iff the operator  $\mathcal{A} - \lambda I$  is degenerate (singular), that is,  $\det(A - \lambda E) = 0.$ 

The characteristic polynomial of  $\mathcal{A}$  is  $f_{\mathcal{A}}(\lambda) = (-1)^n \det(A - \lambda E).$ 

Eigenvalues are exactly the roots of the characteristic polynomial!